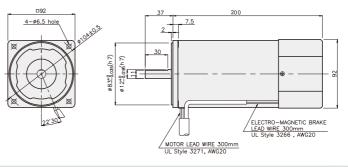
GGM GGM GEARED MOTOR



K9□S200F□-B





200W continuous rating, four poles

Mode	Model		Voltage (V)	Frequency (Hz)	Current (A)	Start T. (N∗m/ Kgf∗cm)	Rated T. (N∗m/ Kgf∗cm)	Speed (rpm)	Condenser (µF)	Friction T. (N*m/ (Kgf*cm)		
K9I□200FT-B			200	50	1.62	4/40	1.5/15	1300	_	1/10		
Kaili 200F I-B			200	60	1.29	3.15/31.5	1.22/12.1	1600		1/10		
			220	50	1.36	4.25/42.5	1.45/14.5	1350	_			
K9I□200FH-B			220	60	1.06	3.4/34	1.22/12.2	1600		1/10		
Kaili 200FH-B		continuous	220	50	1.51	4.3/43	1.45/14.5	1350	_			
			230	60	1,15	3.5/35	1.22/12.2	1600				
K9I□200FM-B	three-phase		continuous	continuous	380	50	0.81	4.3/43	1.45/45.5	1350	_	1/10
K9ILIZUUFM-B			300	60	0.58	3.6/36	1.22/12.2	1600		1/10		
K9I□200FV-B			100	50	0,91	4.5/45	1.45/14.5	1350	_	1/10		
K9ILIZUUFV-B			400	60	0.67	4/40	1.22/12.2	1600		1/10		
K9I□200FQB			415	50	0.62	3.8/38	1.5/15	1300	_	1/10		
K9ID200FQ-B			415	60	0.58	3/30	1.26/12.6	1550		1/10		
K9I□200FZ-B			440	50	0.68	4.1/41	1.5/15	1300	_	1/10		
K91LIZUUFZ-B			440	60	0.54	3/30	1.22/12.2	1600		1/10		

* 🗆 : SHAFT SHAPE (S : STRAIGHT, P : PINION) * FH-B which are in end of the model name is UL certified ones.UL FILE NO. E204632

* 3 phase motor for over 380 voltage can't be used with inverter. Motor winding insulation can be damaged.

• 50Hz																					unit =	above	: N·m / t	below : k	≺gf∙cm
Model	Speed(rpm)	500	416	300	250	200	166	150	120	100	83	75	60	50	41	37	30	25	20	16	15	13	10	8.3	7.5
Motor/ Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9IP20	0F□-B	3.52	4.23	5.87	7.05	8.81	10,57	11,75	13,21	15,86	19.03	21.14	23,78	28.54	30	30	30	30	30	30	30	30	30	30	30
K9P□B	BU, BUF	35.2	42,3	58.7	70,5	88.1	105.7	117.5	132,1	158,6	190,3	211,4	237.8	285.4	300	300	300	300	300	300	300	300	300	300	300

60Hz

• 60Hz																					unit =	above	:N·m / t	below : I	Kgf∙cm
Model	Speed(rpm)	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
Motor/ Gearhead	Ratio	3	3.6	5	6	7.5	9	10	12,5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
K9IP200	0F□−B	2,96	3,56	4.94	5,93	7.41	8,89	9,88	11,12	13,34	16 <u>.</u> 01	17,79	20,01	24.01	28,82	30	30	30	30	30	30	30	30	30	30
К9Р□В	U, BUF	29.6	35.6	49.4	59 <u>.</u> 3	74 <u>.</u> 1	88.9	98.8	111_2	133.4	160_1	177.9	200.1	240.1	288.2	300	300	300	300	300	300	300	300	300	300

* Gearhead and decimal gearhead are sold separately. * The code in
of gearhead model is for gear ratio.
* color indicates that the output shaft of the geared motor rotates in the same direction as the output shaft of the motor. Others indicate rotation in the opposite direction.

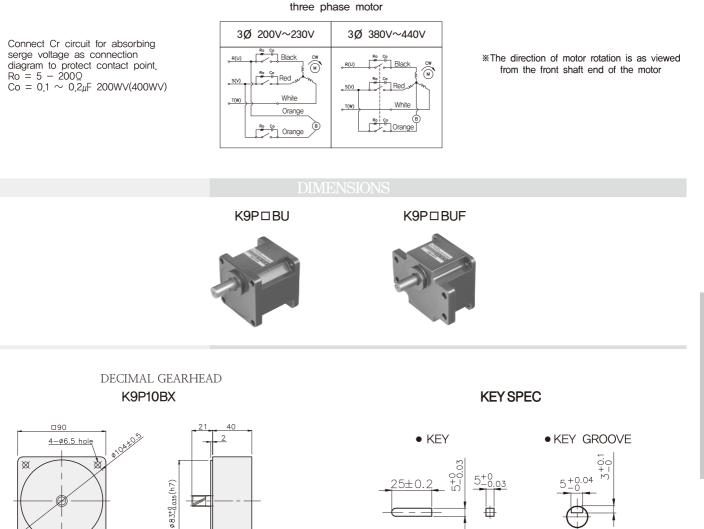
If you are to have less ratio than the ratio in the table, you can install the decimal gearhead, which has one tenth of the ratio, between the gearhead and the motor. In this case, the permissible torque is 30N m/300kgf cm.
 RPM is based on motor's synchronous rpm (50HZ:1500rpm, 60HZ:1800rpm) and calculated by dividing gear ratio. Actual rpm is 2~20% less than

indicating rpm according to load size.



GGM GGM GEARED MOTOR

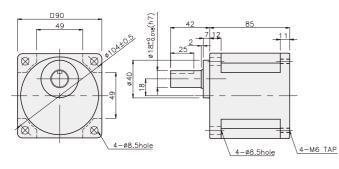
CONNECTION DIAGRAMS



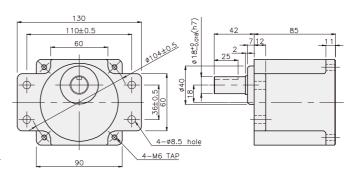
GEARHEAD

K9P□BU

 \boxtimes



K9P□BUF



D-31

GGM GGM GEARED MOTOR GEARHEADS

DIMENSIONS

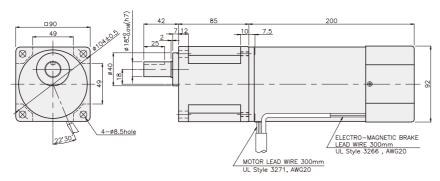
K9 D P 200 F D + K9 P D B U



K9□P200F□ + K9P□BUF



K9IP200F□−B + K9P□BU



WEIGHT

PART	WEIGHT(kg)
MOTOR	4,38
DECIMAL GEAR HEAD	0.62

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	85	K9P3~200BU	M6 P1.0 X 20
02	40	K9P10BX	M6 P1.0 X 60

WEIGHT

PART	WEIGHT(kg)
K9P3~10BU	1,44
K9P12,5~20BU	1,55
K9P25~60BU	1,69
K9P75~200BU	1,74

DIMENSION TABLE

PART No	L	Application Model	Mounting BOLT
01	85	K9P3~200BUF	M6 P1.0 X 20
02	40	K9P10BX	M6 P1.0 X 65

WEIGHT

PART	WEIGHT(kg)
K9P3~10BUF	1,50
K9P12,5~20BUF	1.62
K9P25~60BUF	1,76
K9P75~200BUF	1,82

K9IP200F□−B + K9P□BUF

